# PENKO Engineering B.V.

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## How to... Connect a 1020 to a PC or PLC using RS232 and the ASCII protocol



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### Connect the 1020's to the PC using a straight RS232 cable.







#### Setting up the 1020 with PI Mach II

Connect the 1020 via a USB-cable to the PC. Open Pi Mach II and click on Start Quick setup.

n <sup>7</sup> Indicator 1020, Device Version: 01.03, Build: 03, Serial: 13100008, Module Version: 00.00, Build: 00, Project: C:\Pi test\			
File Project Environment View Tools Help			
📔 💕 On-Line 🛛 🛞 Eirmware Update Manager 🚡 Program Builder 🧠 Flex Builder 🗔 📈	atches 🚽 🛃 E <u>x</u> it		
🗍 💷 Display 📔 🍉 Control 🌒 Tasks 🛛 🥦 1/0 📪 Indigator & Registers 👄 Labels 🚆	Results 🛛 🗰 Printer Layout 👼 Printer Ticket 🛛 🕓 Clock 🗠 Scope		
	Class: Penko 1020 Path: 1		
- 1.3 Enable Full setup			
⊡-Live ⊕-Indicator	Name		
⊕- Digital inputs ⊕- Digital outputs	Start Quick setup		
	Enable Full setup		
⊕ Totals			
i ⊡- System ⊡- Info			
	Discover Import Properties (CSV)		
ACTIVE Ethernet Address: 192.168.151.62 UDP open	Alive: Min: 9 - Time-up: Min: 9 - Resets: 0		

#### Double click on **Communication**.

<sup>2</sup> Indicator 1020, Device Version: 01.03, Build	ild: 03, Serial: 13100008, Module Version: 03.19, Build: 01, Project: C:\Pi test\	
File Project Environment View Tools Hel	elp	
💕 On-Line 🛛 🝥 Eirmware Update Manager	r 🔁 Program Builder 🧠 Fjex Builder 🔲 🔟 atches 🛛 🦪 Exit	
💻 Display 🛛 🕨 Control 🌰 Tasks 🛛 🏪 I	1/0 🛤 Indigator & Registers 🗩 Labels 🚆 Results 🛛 🏭 Printer Layout 🍶 Printer Ticket 🛛 🕓 Glock 🗠 Scope 🛛 🏠 Manage	
<ul> <li>□ Penko 1020         <ul> <li>1.1 Name =</li> <li>1.2 Start Quick setup</li> <li>1.3 Enable Full setup</li> </ul> </li> <li>□ Table Full setup</li> <li>□ Live         <ul> <li>□ Digital outputs</li> <li>⊕ Indicator</li> <li>⊕ Digital outputs</li> <li>⊕ Analog output</li> <li>⊕ Totals</li> <li>□ System</li> <li>⊕ Indicator</li> <li>⊕ System Setup</li> <li>⊕ Ethernet</li> <li>⊕ Ethernet BusLink</li> <li>⊕ RS232</li> <li>⊕ RA22</li> <li>⊕ CAN</li> <li>⊕ Digital inputs</li> </ul> </li> </ul>	Class: Penko 1020.System Setup.Communication Path: 1.3.3	
er Jigitai outputs er Analog output er Passwords	Discours Toward Brogenius (CSV)	ňosly.
	Liscover	мрріу
ACTIVE USB	USB open 94% Done Alive: Min: 19 - Time-up: Min: 19 - Resets: 0	



#### Double click on **RS232**.

Set the parameters as below and click on **Apply** in the bottom right corner. The 1020 is set up correctly.

m² Indicator 1020, Device Version: 01.03, Build: 03, Serial: 13100008, Module Version: 03.19, Build: 01, Project: Ct/Pi test			
File Project Environment View Tools Help			
📔 💕 On-Line 🛛 🛞 Eirmware Update Manager 🗧 Program Builder 🧠 Flex Builder 🔲 😡	atches 🛃 E <u>x</u> it		
📗 🖳 Display 🛛 🕨 Control 🌰 Tasks 🛛 🏪 1/0 📪 Indigator & Registers 📼 Labels 📰	Results 🛛 🏭 Printer Layout 进 Printer T	icket 🕓 <u>C</u> lock 🗠 <u>S</u> cope 📴 Manage	
Penko 1020     1.1 Name =	Class: Penko 1020.System S Path: 1.3.3.4	Setup.Communication.RS232	
- 1.2 Start Quick setup - 1.3 Enable Full setup			
⊟-Live	Protocol	ASCII	
⊕ Digital inputs ⊕ Digital outputs	Address	1	
Analog output	Stopbits	2	
E Totals ≡	Parity	None	
⊡- System ⊕- Info	Baudrate	57600	
⊡- System Setup ⊕- Service	Indicator	1	
⊕- Indicator ⊟- Communication			
Ethernet			
E CAN			
⊡-Digital inputs			
Analog output	Discover Import Proper	rties (CSV)	Apply
	% Done Aliver Min: 2 - Time-un	Min 2 - Paretr 0	
Dog open 100	Anve: Min: 2 - Time-up:	WITH 2 - NESELS V	



#### How to use the ASCII commands

In the example below we use HyperTerminal to get the Gross weight of Indicator 1. The weight of indicator 1 is 3.466kg.

#### HyperTerminal port setting:

Eigenschappen van COM1	
Poortinstellingen	
Bits per seconde: 57600	
Databits: 8	
Pariteit: Geen 🔻	
Stopbits: 1	
Datatransportbesturing: Hardware	
Standaardinstellingen herstellen	
OK Annuleren Toepassen	
Eigenschappen van Penko	ASCII Setup
Connect To Settings	ASCII Sending
Function, arrow, and ctrl keys act as	Send line ends with line feeds
Terminal keys Windows keys	Echo typed characters locally
Backspace key sends	
	Character delay: 0 milliseconds.
Emulation:	ASCII Receiving
Auto detect   Terminal Setup	Append line feeds to incoming line ends
Telnet terminal ID: ANSI	Force incoming data to 7-bit ASCII
	Wrap lines that exceed terminal width
Pray sound when connecting or disconnecting	
ASCII Setup	



Send **OP 1** press "enter" (this will Open Port 1)

You will get an answer back (this will be **OK** if everything went OK or an **Err** if it didn't work.

Send GG press "enter" (this will ask the Gross Weight of indicator 1)

You will get an answer back G+03.466 (the answer you will receive always consists of 5 numbers and the

Send CL press "enter" (this will close the last used port.)

🍓 Penko - HyperTermin	al				×
File Edit View Call	Transfer H	elp			
D 🛩 🌚 🌋 🗈 i	<del>'</del> 1				
					- ^
OF 1 OK GG G+03.466 CL -					THE STREET
			1	•	
Connected 0:00:22	Auto detect	57600 8-N-1	SCROLL	CAPS	IL

Supported ASCII commands

The following commands are available in the ASCII protocol.

#### **Open/Close connection**

Use these commands to open or close a connection.

Device address > 0 and < 255			
Request	Reply	Description	
OP <sub>[space]</sub> 1 <cr></cr>	OK <cr></cr>	Open connection to device with address = 1	
OP <cr></cr>	O:001 <cr></cr>	Check open connection	
CL <cr></cr>		Close connection, no reply	
OP <cr></cr>		Check open connection, no reply so no	
		connection	





#### Device address 0

#### Always open mode

#### Open or close connection is not possible. The connection is always open.

Request	Reply	Description
OP <cr></cr>	0:000 <cr></cr>	Check open connection, connection is always open if device address is 0
CL <cr></cr>		Close connection not possible, is always open, no reply

#### Device address 255

Auto transmit mode

#### Open or close connection is not possible. The connection is always open.

#### The instrument will send the selected indicator value continuously.

Request	Reply	Description
OP <cr></cr>		Open connection not possible, connection is
		always open if device address is 255
CL <cr></cr>		Close connection not possible, is always open,
		auto reply



#### **MIB commands**

When a device is equipped with MIB, all properties can be reached with the MIB ASCII commands. The MIB paths can be found in Manage in PI Mach II. Properties can hold a value, a string or an enumeration.





Request	Reply	Description
MIB available?		
GM <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Check if MIB interface is available
Values		
GM1.1.1.1.3.1.1 <cr></cr>	M1.1.1.1.3.1.1: 2.212kg <cr></cr>	Get MIB property Weigher
GM1.1.1.3.2.1.1.2 <cr></cr>	M1.1.1.3.2.1.1.2: 10.020kg	Get MIB property Maxload
GM1.1.1.3.2.1.1.2=10050 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set MIB property Maxload
Strings		
GM1.1.1.3.2.1.1.1 <cr></cr>	M1.1.1.3.2.1.1.1:Silo weigher <cr></cr>	Get MIB property Name
GM1.1.1.3.2.1.1.1=Silo 2 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set MIB property Name
Enumerations		
GM1.1.1.3.2.1.1.4 <cr></cr>	M1.1.1.3.2.1.1.4:8 <cr></cr>	Get MIB property Sample rate
GM1.1.1.3.2.1.1.4=6 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set MIB property Sample rate
		(Enumerations always start at 0. Sample
		rate for example has 9 options. The
		options correspond with values 0 - 8)
Auto repeat		
SM1.1.1.1.3.1.1 <cr></cr>	M1.1.1.1.3.1.1: 2.212kg <cr></cr>	Set auto repeat read MIB property



#### Interpreter commands

The interpreter commands are available on the FLEX series, 1020 series and SGM700 series.

Request	Reply	Description
Interpreter Extended Register		
IX <cr></cr>	X000900 <cr></cr>	Get number of registers
IX <sub>[space]</sub> 5: <sub>[space]</sub> 1234 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set register 5
IX <sub>[space]</sub> 5 <cr></cr>	X001234 <cr></cr>	Get register 5
Recipe parameters		
IR <cr></cr>	R000014 <cr></cr>	Get number of recipes
IR <sub>[space]</sub> 3: <sub>[space/sign]</sub> 1234 <cr></cr>	OK <cr>/ ERR<cr></cr></cr>	Set recipe value 3 [*1]
IR <sub>[space]</sub> 3 <cr></cr>	R001234 <cr></cr>	Get recipe value 3 [*1]
Indicators		
II <cr></cr>	1000030 <cr></cr>	Get number of indicators
II <sub>[space]</sub> 18: <sub>[space/sign]</sub> 1234 <cr></cr>	OK <cr>/ ERR<cr></cr></cr>	Set indicator 18
II <sub>[space]</sub> 18 <cr></cr>	I+01234 <cr></cr>	Get indicator 18
II <sub>[space]</sub> 19 <cr></cr>	I <cr></cr>	Get indicator 19 (=not available)
Inputs, Outputs and Marker		
IM <cr></cr>	IM001000 <cr></cr>	Get number of I/O/M
$IM_{[space]}401:_{[space]}1 < CR >$	OK <cr>/ ERR<cr></cr></cr>	Set marker 401
IM <sub>[space]</sub> 401 <cr></cr>	IM 00100000 <cr></cr>	Get markers 401408
IM <sub>[space]</sub> 409: <sub>[space]</sub> 0 <cr></cr>	OK <cr>/ ERR<cr></cr></cr>	Reset marker 409
Query and Mark result		
I= <cr></cr>	=+00029+001000121<	Query result value
	CR>	Result index: +00029
		Result value: +00100
		Result tag: 01 (hex format)
		Checksum: 21(hex format)
I= <sub>[space]</sub> 29 <cr></cr>	OK <cr>/ ERR<cr></cr></cr>	Mark result value (=delete)

\*1 - Not supported on 1020 series and SGM700 series



#### **Calibration commands**

The calibration commands are <u>not</u> available on the FLEX series.

Request	Reply	Description
Calibration support		
CE <cr></cr>	E000002 <cr></cr>	Get CAL code
CE <sub>[space]</sub> 02 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Enter CAL code
CZ <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set zero value
CG <sub>[space]</sub> 0500 <cr> ( value)</cr>	OK <cr>/ERR<cr></cr></cr>	Set gain value
CS <cr></cr>	OK <cr>/ ERR<cr></cr></cr>	Save calibration
CM <cr></cr>	M+10009 <cr></cr>	Get max load
CM <sub>[space]</sub> 10009 <cr> (value)</cr>	OK <cr>/ERR<cr></cr></cr>	Set max load

When using the ASCII protocol for calibration, follow these steps.

- Empty the weigher
- Enter CE<CR> to get the CAL code // Reply for example E000003
- Enter CE 3<CR>
- Enter CZ<CR> to set the zero point
- Load the weigher // For example 500kg
- Enter CE<CR> to get the CAL code // Replay for example E000004
- Enter CE 4<CR>
- Enter CG 500<CR> to set the gain point
- Enter CS<CR> to save the calibration



#### **Configuration commands**

The configuration commands are <u>not</u> available on the FLEX series.

Request	Reply	Description
s/w damping factor		
FL <cr></cr>	F000005 <cr></cr>	Get s/w damping factor (overall filter)
FL <sub>[space]</sub> 5 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set s/w damping factor (overall filter)
Virtual display support		
DR <cr></cr>	R000004 <cr></cr>	Get display refresh rate
DR <sub>[space]</sub> 4 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set display refresh rate
DS <cr></cr>	S000006 <cr></cr>	Get weigher format step size
DS <sub>[space]</sub> 6 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set weigher format step size
DP <cr></cr>	D000003 <cr></cr>	Get weigher format decimal point position
DP <sub>[space]</sub> 3 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set weigher format decimal point position
Display filter support		
DD <cr></cr>	D000006 <cr></cr>	Get display filter damping
DD <sub>[space]</sub> 6 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set display filter damping
DZ <cr></cr>	Z+00.050 <cr></cr>	Get display zero suppress
DZ <sub>[space]</sub> 00050 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set display zero suppress
DA <cr></cr>	A+00.060 <cr></cr>	Get display filter range
DA <sub>[space]</sub> 00060 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set display filter range
Zero-tracking support		
TR <cr></cr>	R+00.020 <cr></cr>	Get zero tracking range
TR <sub>[space]</sub> 00020 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set zero tracking range
TS <cr></cr>	S+00.020 <cr></cr>	Get zero tracking step
TS <sub>[space]</sub> 00020 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set zero tracking step
TT <cr></cr>	T000020 <cr></cr>	Get zero tracking time
TT <sub>[space]</sub> 000020 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set zero tracking time
No-motion/stable support		
NR <cr></cr>	R+00.002 <cr></cr>	Get stable range
NR <sub>[space]</sub> 00002 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set stable range
NT <cr></cr>	T000100 <cr></cr>	Get stable time
NT <sub>[space]</sub> 000100 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set stable time



#### Weighing commands

The weighing commands are available on the FLEX series, 1020 series and SGM700 series.

Request	Reply	Description	
Current display value			
SD <cr></cr>	+02.212 <cr>/ERR<cr></cr></cr>	Set auto-transmit Display value	
GD <cr></cr>	+02.212 <cr>/ERR<cr></cr></cr>	Get Display value	
Set/reset system zero			
SZ <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set Zero	
RZ <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Reset Zero	
Set/reset tare			
ST <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set Tare	
RT <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Reset Tare	
Reset peak/valley			
RP <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Reset Peak	
RV <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Reset Valley	
Get various channels			
GN <cr></cr>	N+00.456 <cr></cr>	Get net	
GG <cr></cr>	G+00.694 <cr></cr>	Get gross	
GT <cr></cr>	T+00.238 <cr></cr>	Get tare	
GP <cr></cr>	P+03.074 <cr></cr>	Get peak	
GV <cr></cr>	V+00.082 <cr></cr>	Get valley	
GF <cr></cr>	F+00.456 <cr></cr>	Get fast net (no display damping)	
GS <cr></cr>	S000.985 <cr></cr>	Get A/D sample	
GX <cr></cr>	X+0.0456 <cr></cr>	Get extended net (net x 10)	
Long string commands			
GW <cr></cr>	W+00456+006944CD9 <cr></cr>	Get fast net+gross, status & checksum	
LW <cr></cr>	W+00456+006944CD9 <cr></cr>	Get long net+gross, status & checksum	
LN <cr></cr>	N+00456+004564CE6 <cr></cr>	Get net+fast net , status & checksum	
LF <cr></cr>	F+00456+006944CEA <cr></cr>	Get long fast net+gross, status & checksum	
LX <cr></cr>	X+04556+069364CCE <cr></cr>	Get long extended net (net x 10) + extended gross	
		(gross x 10), status & checksum	
Auto-transmit mode suppo	rt		
SN <cr></cr>	N+00.456 <cr></cr>	Set auto-transmit net	
SG <cr></cr>	G+00.694 <cr></cr>	Set auto-transmit gross	
SW <cr></cr>	W+00456+006944CD9 <cr></cr>	Set auto-transmit long weight	
SP <cr></cr>	P+03.074 <cr></cr>	Set auto-transmit peak	
SV <cr></cr>	V-00.082 <cr></cr>	Set auto-transmit valley	
SF <cr></cr>	F+00.456 <cr></cr>	Set auto-transmit fast net	
SX <cr></cr>	X+0.0456 <cr></cr>	Set auto-transmit extended net (net x 10)	
Weigher preset tare support			
PI <cr></cr>	P+00.231 <cr></cr>	Get preset tare value	
PI <sub>[space]</sub> 00231 <cr></cr>	OK <cr>/ERR<cr></cr></cr>	Set preset tare value	
PS <uk></uk>		Set preset tare on	
		Stub function to fool SAIASSI	
	V:0101 <cb></cb>	Catvarsian number	
	V.UIUI <cn></cn>	Get version number	
	2.001000 <ck></ck>	Get device ID code	



#### Status and checksum

The long string commands return 2 weigher values, status and checksum. The status and checksum are represented in a hexadecimal format.

For example, the command GW<CR> returns W+00324+003244CE9<CR> where "4C" represents the status bits and "E9" represents the checksum. Status bits:

Bit #	Called	Definition
0	Hardware overload	Hardware overload/underload detected on load cell
1	Maximum load	Overload detected on load cell
2	Stable weight	Weigher signal is stable
3	Stable range	Weigher signal is in stable range
4	Zero set	Weigher zero is corrected
5	Zero center	Weigher in center of zero range
6	Zero range	Weigher is in zero range, zero is possible
7	Zero track range	Weigher signal is in zero tracking range, zero tracking is possible

"4C" from the example is binary 0100 1100, so stable weight, stable range and zero range are active.

The checksum is the inverted sum of all ASCII characters. The return value W+00324+003244C from the example:

#### W + + + 0 + 0 + 3 + 2 + 4 + + + 0 + 0 + 3 + 2 + 4 + 4 + C =

#### 57+2B+30+30+33+32+34+2B+30+30+33+32+34+34+43 = 316 (hex)

Remove the most significant digit = 16 (hex)

Invert the hex value = E9

Convert the hex value E9 to ASCII characters 'E' and '9'



#### Setup example

#### MIB setup RS232 address 0, indicator 1

```
    RS232
    1.3.3.4.1 Protocol = ASCII
    1.3.3.4.2 Address = 0
    1.3.3.4.3 Stopbits = 1
    1.3.3.4.4 Parity = None
    1.3.3.4.5 Baudrate = 115200
    1.3.3.4.6 Indicator = 1
```

#### MIB setup RS232 address 255(=auto transmit), indicator 8

. → RS232





#### About PENKO

Our design expertise include systems for manufacturing plants, bulk weighing, check weighing, force measuring and process control. For over 35 years, PENKO Engineering B.V. has been at the forefront of development and production of high-accuracy, high-speed weighing systems and our solutions continue to help cut costs, increase ROI and drive profits for some of the largest global brands, such as Cargill, Sara Lee, Heinz, Kraft Foods and Unilever to name but a few.

Whether you are looking for a simple stand-alone weighing system or a high-speed weighing and dosing controller for a complex automated production line, PENKO has a comprehensive range of standard solutions you can rely on.

#### Certifications

PENKO sets high standards for its products and product performance which are tested, certified and approved by independent expert and government organizations to ensure they meet – and even – exceed metrology industry guidelines. A library of testing certificates is available for reference on:

http://penko.com/nl/publications\_certificates.html

#### **PENKO Professional Services**

PENKO is committed to ensuring every system is installed, tested, programmed, commissioned and operational to client specifications. Our engineers, at our weighing center in Ede, Netherlands, as well as our distributors around the world, strive to solve most weighing-system issues within the same day. On a monthly basis PENKO offers free training classes to anyone interested in exploring modern, high-speed weighing instruments and solutions. A schedule of training sessions is found on: www.penko.com/training

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